During the downward movement :

If the motor reaches an obstacle during the downward movement, it stops automatically its movement and return back from an half turn in order to free the obstacle.

In order to have a reliable obstacle detection, it's important to follow the abacus:

- -If the motor is too sensitive \rightarrow the risk is to have false stops
- -If the motor is not enough sensitive \rightarrow the risk is to not detect an obstacle

The obstacle detection is activated during all the downward movement

During the upward movement :

An obstacle detection is also activated during the upward movement (Like an Oximo : stop + back release)

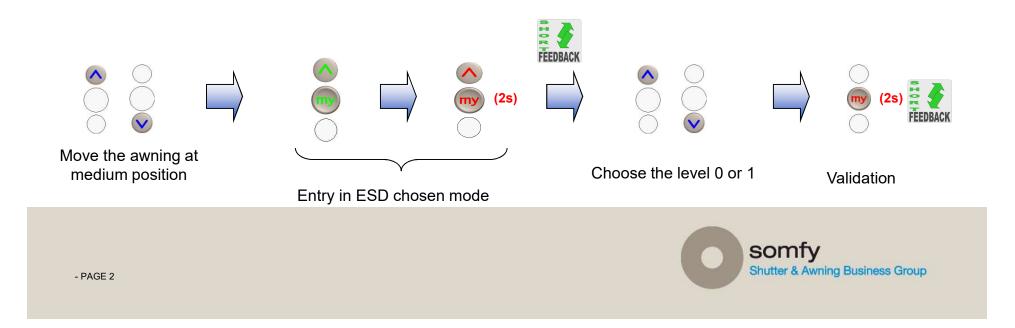


Obstacle detection during the downward movement : Deactivation / Activation

Obstacle Detection: deactivation / Activation

This function give the possibility for our customer to deactivate the obstacle detection during the downward movement in case of untimely stops (Load bar very slight for example)

By **security**, this function is activate by default, and can being deactivate through a remote control ergonomic (*when the application is in a middle position*)



Obstacle detection during the downward movement :

